PopArt: Efficient Sparse Regression and Experimental Design for Optimal Sparse Linear Bandits

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Problem: sparse linear bandits

- For time step $t = 1, 2, \ldots T$:
 - Take an action a_t from action space $\mathcal{A} \subseteq [-1, +1]^d$
 - Receive reward $r_t = \langle \theta_*, a_t \rangle + \eta_t$

 $\langle \theta_*, a \rangle$ a_t r_t

User



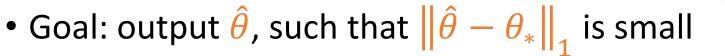
• Goal: minimize cumulative regret $\sum_{t=1}^{T} \max_{a \in \mathcal{A}} \langle \theta_*, a \rangle - \langle \theta_*, a_t \rangle$

zero mean, 1-subgaussian noise

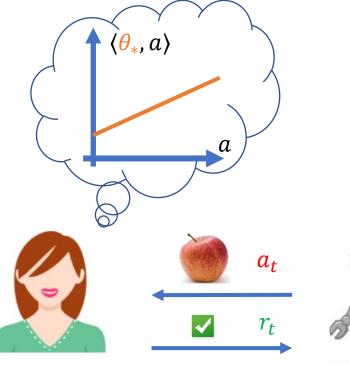
- Tradeoff between exploration and exploitation
- θ_* is sparse

Problem: experimental design for sparse recovery

- For time step t = 1, 2, ... T:
 - Make a measurement a_t from $\mathcal{A} \subseteq [-1, +1]^d$
 - Receive noisy response $r_t = \langle \theta_*, a_t \rangle + \eta_t$



- Assumption: θ_* is *sparse*
- No exploration / exploitation tradeoff

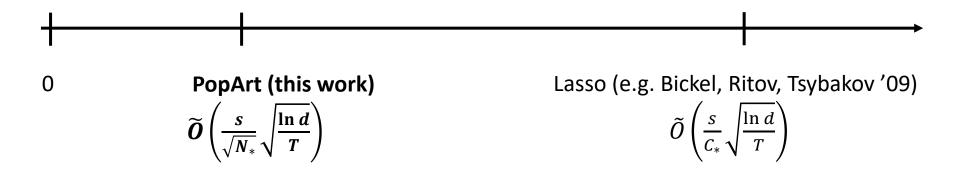


User

Learner

Main result: experimental design for sparse recovery

- Assumption: θ_* is *s*-sparse ($s \ll d$)
- ℓ_1 -recovery error guarantee:



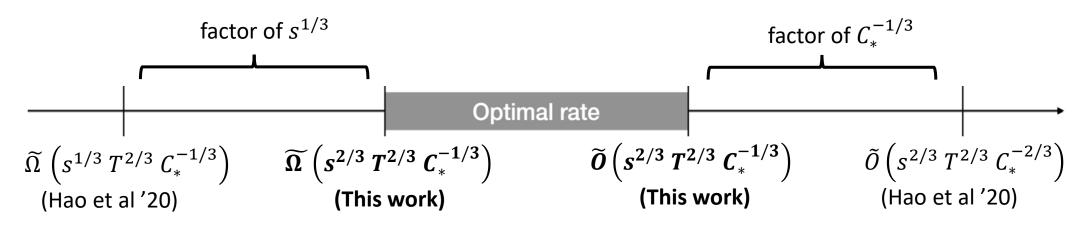
0 *C*.

Ν.,

- $C_* = \max_{\pi \in \Delta(\mathcal{A})} \lambda_{\min}(Q(\pi)), \ Q(\pi) = \mathbb{E}_{a \sim \pi}[aa^{\top}]$
- N_* is a new measurement set-dependent quantity
 - $N_* \ge C_*$ and can be $\gg C_*$

Main result: sparse linear bandits in datapoor regime

• Assumption: θ_* is s-sparse ($s \ll d$) and T is small ($T \ll d$)

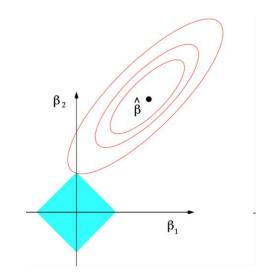


• Additional result:

•
$$\widetilde{\Theta}\left(s^{2/3}T^{2/3}N_{*}^{-1/3}\right)$$
 regret upper and lower bounds

PopArt: new algorithm for sparse estimation

- Sparse estimation
 - Given: iid (a_t, r_t) 's such that $r_t = \langle \theta_*, a_t \rangle + \eta_t, \theta_*$ is s-sparse
 - Goal: recover θ_*
- Predominant approach: Lasso (Tibshirani'96) $\min_{\theta} \sum_{t} (r_t - \langle \theta, a_t \rangle)^2 + \lambda \|\theta\|_1$



Decision

Data

Prediction

- Our approach: POPulation covariance regression with hARd Thresholding (PopArt)
 - Key insight: in many applications, the population covariance matrix, $Q = \mathbb{E}[aa^T]$ is known and can be utilized Algorithm

PopArt: the algorithm

• Key insight (Dani, Hayes, Kakade '07):

 $\tilde{\theta}_t = Q^{-1}(a_t r_t)$ is an unbiased estimator of θ_*

PopArt

Compute $\tilde{\theta}_t, t = 1, ..., T$ For i = 1, 2, ..., d: $\tilde{\theta}^i \leftarrow \text{Robust-mean-estimator}(\tilde{\theta}_1^i, ..., \tilde{\theta}_T^i)$ (Catoni '12) Return $H_s(\tilde{\theta})$.

 H_2

- H_s : hard thresholding operator
 - Brings $\tilde{\theta}$ closer to θ^* in ℓ_1 distance, by exploiting sparsity of θ^*

PopArt: recovery guarantee

• **Theorem:** (some variant of) PopArt outputs $\hat{\theta}$ that has ℓ_1 recovery error

$$\left\|\hat{\theta} - \theta_*\right\|_1 \le \tilde{O}\left(s\sqrt{\max_i (Q^{-1})_{ii}}\sqrt{\frac{\ln d}{T}}\right)$$

with high probability.

Experimental design for PopArt

$$\left\|\hat{\theta} - \theta_*\right\|_1 \le \tilde{O}\left(s\sqrt{\max_i (Q^{-1})_{ii}}\sqrt{\frac{\ln d}{T}}\right)$$

• Given measurement set \mathcal{A} , minimize recovery bound by design sampling distribution

$$u^* = \operatorname*{argmin}_{\pi \in \Delta(\mathcal{A})} \max_{i} (Q(\pi)^{-1})_{ii}$$

- New experimental design criterion -> computationally tractable
- **Corollary:** PopArt with *T* samples from has ℓ_1 recovery error $\tilde{O}\left(\frac{s}{\sqrt{N_*}}\sqrt{\frac{\ln d}{T}}\right)$, where

$$N_* = \max_{\pi \in \Delta(\mathcal{A})} \min_{i} \frac{1}{(Q(\pi)^{-1})_{ii}}$$

Sparse linear bandits: algorithm & lower bounds

Optimal rate $\widetilde{\Omega}\left(s^{2/3} T^{2/3} C_{*}^{-1/3}\right) \qquad \widetilde{O}\left(s^{2/3} T^{2/3} C_{*}^{-1/3}\right)$

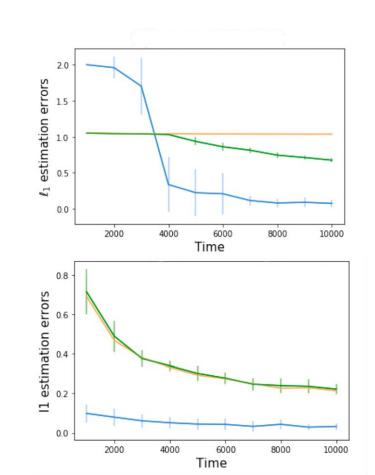
(This work)

(This work)

- New algorithm & regret upper bound: explore-then-commit
 - Use PopArt with μ^* for exploration
- New regret lower bound:
 - Main idea: reducing to lower bound sample complexity of estimating support(θ^*)
 - Prior work (Hao et al, 2020): use binary hypothesis testing
 - This work: using *symmetrization* to improve lower bound by a $s^{1/3}$ factor

Numerical simulations

- Sparse recovery algorithms evaluated:
 - PopArt with μ^* experimental design
 - Lasso with μ^* experimental design
 - Lasso with E-optimal design
- Experiment 1: d = 10, s = 2an \mathcal{A} with $N_* \gg C_*$
- Experiment 2: d = 30, s = 2 \mathcal{A} consists of 90 unit vectors ($N_* \approx C_*$)



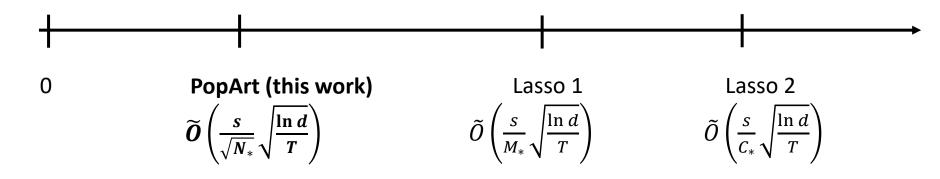
Conclusions & future work

- We propose PopArt, a new sparse estimation algorithm that can have better recovery guarantees than classical Lasso
- PopArt motivates a new experimental design criterion, and yields an optimal sparse linear bandit algorithm (in data-poor regime)
- Ongoing work: new estimator & experimental design for low-rank matrix regression
- Open questions:
 - (experimental design) Fixed measurement set A and budget T, can we design estimators with even lower recovery error?
 - (bandits) what's the minimax regret for sparse linear bandits in all regimes of parameters?
- Thank you! Paper: https://arxiv.org/abs/2210.15345

Backup

Main result: experimental design for sparse recovery

- Assumption: θ_* is *s*-sparse
- ℓ_1 -recovery error guarantee:



•
$$M_* = \max_{\pi \in \Delta(\mathcal{A})} \phi_0^2(Q(\pi), s)$$
 – restricted eigenvalue

- Intractable Experimental design criterion (Bandeira et al, 2012)
- Proposition: exists \mathcal{A} , such that $\frac{1}{\sqrt{N_*}} \ll \frac{1}{M_*}$

Definition of N_*

•
$$N_* = \max_{\pi \in \Delta(\mathcal{A})} \min_i \frac{1}{(Q(\pi)^{-1})_{ii}}$$

• $\max_{\pi \in \Delta(\mathcal{A})} \min_{i} \frac{1}{(Q(\pi)^{-1})_{ii}}$

PopArt: recovery guarantee

• **Theorem:** (some variant of) PopArt outputs $\hat{\theta}$ that has ℓ_1 recovery error

$$\left\|\hat{\theta} - \theta_*\right\|_1 \le \tilde{O}\left(s\sqrt{\max_i (Q^{-1})_{ii}}\sqrt{\frac{\ln d}{T}}\right)$$

with high probability.

- Key idea of analysis:
 - establish bounds on $\left| \tilde{\theta}^i \theta^i_* \right|$ for all coordinate i
 - To this end, analyze variance of $ilde{ heta}_t^i$

 $\tilde{\theta}^i \leftarrow \text{Robust-mean-estimator}(\tilde{\theta}_1^i, \dots, \tilde{\theta}_T^i)$

Sparse linear bandits: algorithm & lower bounds



• New algorithm & regret upper bound: explore-then-commit

First T_1 rounds: take $a_t \sim \pi^*$, see r_t use PopArt to compute $\hat{\theta}$

Remaining $T - T_1$ rounds: take $a_t = \operatorname{argmax}_{a \in \mathcal{A}} \langle \hat{\theta}, a \rangle$

- New regret lower bound:
 - Main idea: reducing to lower bound sample complexity of estimating support(θ^*)
 - Prior work (Hao et al, 2020): use binary hypothesis testing
 - This work: using *symmetrization* to improve lower bound by *s* factor

Sparse linear bandits: algorithm & lower bounds $\int_{\widetilde{\Omega}(s^{2/3}T^{2/3}C_*^{-1/3})} Optimal rate = \delta(s^{2/3}T^{2/3}C_*^{-1/3})$

• New algorithm & regret upper bound: explore-then-commit

First T_1 rounds: take $a_t \sim \mu^*$, see r_t use PopArt to compute $\hat{\theta}$

Remaining $T - T_1$ rounds: take $a_t = \operatorname{argmax}_{a \in \mathcal{A}} \langle \hat{\theta}, a \rangle$

(This work)

(This work)

- New regret lower bound:
 - Main idea: reducing to lower bound sample complexity of estimating $support(\theta^*)$
 - Prior work (Hao et al, 2020): use binary hypothesis testing
 - This work: using symmetrization to improve lower bound by a $s^{1/3}$ factor