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 Piazza post @t2 (Say a few words about your gas when booking)

Stochastic linear (contextual) bandit

Application: personalized recommendation

For  $t=1, 2, \dots, T$ :

observes  $x_t \in \mathcal{X}$  (context)

takes action  $a_t \in A = \{1, \dots, K\}$

receive reward  $r_t = f(x_t, a_t) + \underline{\epsilon}_t$

$\phi(x, a) = \epsilon_a = \theta \cdot \mathbf{1}_a$  deterministic fn unknown  $\sim N(0, D)$

$$f(x, a) = \langle \underbrace{\theta^*}_{\text{unknown}}, \underbrace{\phi(x, a)}_{\text{known}} \rangle$$

$$\mathbb{E}[r_t] = f(x_t, a_t)$$

$$\text{goal: maximize } \mathbb{E} \left[ \sum_{t=1}^T r_t \right] = \mathbb{E} \left[ \sum_{t=1}^T f(x_t, a_t) \right]$$

performance measure: pseudo-regret

$$R_T = \mathbb{E} \left[ \underbrace{\max_a \sum_{t=1}^T f(x_t, a)}_{\text{optimal}} - \sum_{t=1}^T f(x_t, a_t) \right]$$

$$= \mathbb{E} \left[ \sum_{t=1}^T \max_a (f(x_t, a) + \epsilon_t(a)) - \sum_{t=1}^T (f(x_t, a_t) + \epsilon_t(a_t)) \right]$$

Assume:  $\|\theta^*\|_2 \leq 1$ .  $\forall x, a, \|\phi(x, a)\|_2 \leq 1$ .

... and algorithm w/ small

Q1. How can we design a good algorithm with pseudo regret?

$$\left( x_s, a_s, r_s = \langle \theta^*, \phi(x_s, a_s) \rangle + \epsilon_s \right)_{s=1}^{t-1}$$

can we learn smth about  $\theta^*$ ?

Q2. given  $\hat{\theta}_t$ , how to take actions?

$$a_t = \underset{a \in A}{\operatorname{argmax}} \underbrace{\langle \hat{\theta}_t, \phi(x_t, a) \rangle + \text{exploration}(a)}_{\text{UCB}_t(a)}$$

$$\text{UCB}_t(a) \geq f(x_t, a)$$

$$\text{Q1: } \theta_t(\lambda) = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} \sum_{s=1}^{t-1} (\langle \theta, \phi_s \rangle - r_s)^2 + \lambda \|\theta\|_2^2$$

Informally:  $\theta_t(0) = V_{t-1}^{-1} \left( \sum_{s=1}^{t-1} \phi_s r_s \right)$

$$V_{t-1} = \sum_{s=1}^{t-1} \phi_s \phi_s^\top \quad \phi_s^\top \theta^*$$

$$V_{t-1}^{-1} \quad s=1 \quad \text{Net} \quad r_s = \langle \theta^* \phi_s \rangle + \epsilon_s$$

$$\Theta_t(t_0) = V_{t-1}^{-1} \left( \underbrace{\sum_{s=1}^{t-1} \phi_s \phi_s^T}_{\text{Net}} \theta^* + \sum_{s=1}^{t-1} \phi_s \epsilon_s \right)$$

$$= \theta^* + \underbrace{V_{t-1}^{-1} \sum_{s=1}^{t-1} \phi_s \epsilon_s}_{\text{Net}}$$

$\epsilon_s$   
 $a_{t_j}$   
 $\phi_t$

(\*)  $N(0, V_{t-1})$

$N(0, V_{t-1}^{-1})$

given new  $x, a$ , construct a confidence interval of  $\langle \theta^*, \phi(x, a) \rangle$  based on  $\Theta_t(t_0)$  ?

$$\langle \underbrace{\Theta_t(t_0)}_x, \underbrace{\phi(x, a)}_a \rangle \sim N(\langle \theta^*, \phi(x, a) \rangle, \|\phi(x, a)\|_{V_{t-1}^{-1}}^2)$$

$$X \sim N(0, \Sigma_{aa})$$

$$a^T X \sim N(0, a^T \Sigma a)$$

By subgaussian tail property: w.p.  $1-\delta$ :

$$\left| \langle \theta_{t-1}^{(0)}, \phi(x, a) \rangle - \langle \theta^*, \phi(x, a) \rangle \right|$$

$$\leq \|\phi(x, a)\|_{V_{t-1}^{-1}} \sqrt{\ln \frac{1}{\delta}}$$

$$\Rightarrow \text{UCB}_t(a) = \langle \phi(x, a), \theta_{t-1}^{(0)} \rangle +$$

$$\|\phi(x, a)\|_{V_{t-1}^{-1}} \sqrt{\ln \frac{1}{\delta}}$$

problem: ①  $(\phi_s)_{s=1}^{t-1}$  depend on  $(\Sigma_s)_{s=1}^{t-1}$ ,

(\*) is wrong.

②  $V_{t-1}$  may not be full rank.

Fix: ① (Auer 2002), (Chu, Li, Reyzin, ...)  
 ② specialized binning

Schapire, 2011) :

procedure.

② setting  $\lambda > 0$  in  $\hat{\Theta}_t(\lambda)$ .

$$\text{Q1: } \hat{\Theta}_t(\lambda) = V_{t-1}(\lambda)^{-1} \left( \sum_{s=1}^{t-1} \phi_s r_s \right)$$

$$(V(\lambda) = V + \lambda I)$$

Lemma: define  $\beta_t(\delta) = 1 + \sqrt{2 \ln \frac{1}{\delta} + d \ln \left( \frac{t}{d} \right)}$ ,

then,  $\exists$  event  $E$ ,  $P(E) \geq 1 - \delta$ , and

on  $E$ ,  $(\bar{x}_{t-1}(a))_{a=1}^K$

$$\| \hat{\Theta}_t(\lambda) - \Theta^* \|_{V_{t-1}(\lambda)} \leq \beta_t(\delta)$$

for all  $t$ .

$$\phi(x, a) = e_a$$

$$V_{t-1}(\lambda) = \begin{pmatrix} m_{t-1}(1) + 1 & & \\ & \ddots & \\ & & m_{t-1}(K) + 1 \end{pmatrix}$$

$\leq O(K)$

$$\forall a, \quad |m_{t-1}(a) - p(a)| \leq \frac{1}{m_{t-1}(a)+1}$$

pf:  $\hat{\Theta}_t(l) - \Theta^*$

$$= V_{t-1}^{-1}(l) \left( V_{t-1} \Theta^* + \sum_{s=1}^{t-1} \phi_s \varepsilon_s \right) - \Theta^*$$

$$= V_{t-1}^{-1}(l) \cdot \Theta^* + V_{t-1}^{-1}(l) \sum_{s=1}^{t-1} \phi_s \varepsilon_s$$

$$\| \hat{\Theta}_t(l) - \Theta^* \|_{V_{t-1}(l)}$$

$$\leq \| V_{t-1}^{-1}(l) \Theta^* \|_{V_{t-1}(l)} + \| V_{t-1}^{-1}(l) \sum_{s=1}^{t-1} \phi_s \varepsilon_s \|_{V_{t-1}(l)}$$

defn of Mahalanobis norm

$$= \| \Theta^* \|_{V_{t-1}^{-1}(l)} + \| \sum_{s=1}^{t-1} \phi_s \varepsilon_s \|_{V_{t-1}^{-1}(l)}$$

$$\| A \|_{B^{-1}} \geq \| A \|_B \geq \| A \|_A$$

$$\leq 1 + \sqrt{2 \ln \frac{t}{\delta} + d \ln \left(1 + \frac{t}{d}\right)}$$

self-normalized bound.  
 $\lambda=1$ .

self-normalized bound:

there exists an event  $E$ .  $P(E) \geq 1-\delta$ .

in which

$$\left\| \sum_{s=1}^t \phi_s \varepsilon_s \right\|_{V_t^{-1}(\lambda)} \leq \sqrt{2 \ln \frac{t}{\delta} + d \ln \left(1 + \frac{t}{d}\right)}$$

(Abbasi-Yadkori, Dal, Szepesvári, 2011)

QZ:

$$\mathbb{H}_t = \left\{ \left\| \hat{\theta}_t(\lambda) - \theta \right\|_{V_{t-1}(\lambda)} \leq \beta_t(\delta) \right\}$$

on event  $E$ .  $\theta^* \in \mathbb{H}_t$ .

at time step  $t$ . constant UCB for  
 $\langle \theta^*, \phi(x_t, a) \rangle$  for all  $a$ .

define  $\pi$  on  $\mathbb{E} f(x_t, a)$

$$\underline{\text{UCB}}_t(a) = \max_{\theta \in \Theta_t} \langle \theta, \phi(x_t, a) \rangle$$

$$= \max \langle \hat{\Theta}_t(l) + \delta, \phi(x_t, a) \rangle$$

$$\|\delta\|_{V_{t+1}(l)} \leq \beta_t(\delta).$$

$$= \langle \hat{\Theta}_t(l), \phi(x_t, a) \rangle +$$

$$\beta_t(\delta) \cdot \|\phi(x_t, a)\|_{V_{t+1}^{-1}(l)}$$

uncertainty for this  $(x_t, a)$



MAB

$$\sqrt{k} \cdot \sqrt{\frac{\ln T}{m_{t-1}(a)+1}}$$

Alg:  $a_t = \operatorname{argmax}_{a \in A} \text{UCB}_t(a)$

(LinUCB, OFUL)

Analysis:

Thm: for LinUCB:

$$\sqrt{d \ln T}$$

$$R_T \leq O\left(T \delta + \beta_T(\delta) \sqrt{d \cdot T \ln\left(1 + \frac{T}{d}\right)}\right)$$

setting  $\delta = \frac{1}{T}$   $R_T \leq \tilde{O}(d \sqrt{T})$

(For MAB:  $\phi(x, a) = e_a \in \mathbb{R}^k \rightarrow k \sqrt{T}$ )

$$\text{UCB} \cdot \sqrt{kT}$$

Pf. on event  $\overline{E}$ . contributions to

$$R_T \leq 2T \cdot \delta.$$

on event  $E$ :

$$P_t = \max_a \underline{f(x_t, a)} - f(x_t, a_t)$$

$$= \max_a \text{UCB}_t(a) - f(x_t, a_t)$$

$$= \text{UCB}_t(a_t) - \underline{f(x_t, a_t)}$$

$$= \langle \hat{\theta}_t, \phi_t \rangle + \beta_t(\delta) \|\phi_t\|_{V_t^{-1}}$$

$$- \langle \theta^*, \phi_t \rangle \leq \beta_t$$

$$\|\hat{\theta}_t - \theta^*\|_{V_t^{-1}} \|\phi_t\|_{V_t^{-1}}$$

$$= 2 \beta_t(\delta) \cdot \|\phi_t\|_{V_t^{-1}(1)}$$

$$\leq 2 \beta_t(\delta) \|\phi_t\|_{V_t(\mathcal{I})} \cdot 2.$$

$$(V_t(\mathcal{I}) \leq 2 \cdot V_{t-1}(\mathcal{I}))$$



$$\sum_{t=1}^T \rho_t \leq 4 \beta_t(\delta) \cdot \sum_{t=1}^T \|\phi_t\|_{V_t(\mathcal{I})}$$

$$\stackrel{C-S}{\leq} 4 \beta_t(\delta) \cdot \sqrt{T \cdot \sum_{t=1}^T \|\phi_t\|_{V_t(\mathcal{I})}^2}$$

Elliptic potential

$$\leq 4 \beta_t(\delta) \sqrt{T \ln\left(1 + \frac{T}{d}\right)}$$

~~Next~~,

Next: reinforcement learning.