CSC 588: Machine learning theory

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Lecture 10: Lower bound of sample complexities of VC classes

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## 1 Lower bounds for statistical learning

In previous lectures, it was shown that if we have  $O(\frac{d}{\epsilon^2})$  number of training examples, then ERM has excess error less than  $\epsilon$ . In this lecture, let's consider the opposite region: what if we only have O(d) examples. Note that we will discuss learnability as a property of hypothesis class  $\mathcal{H}$  only.

**Definition 1.**  $\mathcal{H}$  is said to be agnostic PAC learnable if there exists an algorithm  $\mathcal{A}$  and a sample complexity function  $f(\cdot, \cdot)$  such that for any distribution D, for any  $\epsilon, \delta > 0$ , if  $m \ge f(\epsilon, \delta)$ , then with probability  $1 - \delta$  over the draw of m training examples i.i.d. from D,

$$\operatorname{err}(\mathcal{A}(S), D) - \min_{h' \in \mathcal{H}} \operatorname{err}(h', D) \le \epsilon$$

where  $\mathcal{A}(S) = \hat{h}$ .

**Definition 2.**  $\mathcal{H}$  is said to be (realizable) PAC learnable if there exists an algorithm  $\mathcal{A}$  and a sample complexity function  $f(\cdot, \cdot)$  such that for any distribution D realizable by  $\mathcal{H}$ , for any  $\epsilon, \delta > 0$ , if  $m \ge f(\epsilon, \delta)$ , then with probability  $1 - \delta$  over the draw of m training examples i.i.d. from D,

$$\operatorname{err}(\mathcal{A}(S), D) \le \epsilon$$

Finite VC dimension  $\Rightarrow$  uniform convergence  $\Rightarrow$  ERM sample complexity  $O(\frac{d}{\epsilon^2}) \Rightarrow \mathcal{H}$  is PAC learnable The following theorem shows that PAC learnable  $\Rightarrow$  Finite VC dimension

**Theorem 3.** Given a  $\mathcal{H}$  such that  $VC(\mathcal{H}) \geq d$ . If the number of training examples  $m \leq \frac{d}{2}$ , then for any algorithm  $\mathcal{A}$ , there exists a distribution D realizable by  $\mathcal{H}$ 

$$\mathbb{E}_{S \sim D^m} \operatorname{err}(\mathcal{A}(S), D) \ge \frac{1}{4}$$
(1)

**Remark 1.** Eq. (1) also implies that

$$\mathbb{P}_{S \sim D^m}\left(\operatorname{err}(\mathcal{A}(S), D) > \frac{1}{8}\right) \ge \frac{1}{8}$$
(2)

showing that  $\mathcal{A}$  does not  $(\epsilon = \frac{1}{8}, \delta = \frac{1}{9})$ -PAC learn  $\mathcal{H}$  with  $m \leq \frac{d}{2}$  examples. The reason is if  $\mathcal{A}$   $(\epsilon = \frac{1}{8}, \delta = \frac{1}{9})$ -PAC learn  $\mathcal{H}$  with  $m \leq \frac{d}{2}$  example, then

$$\mathbb{P}_{S \sim D^m}\left(\operatorname{err}(\mathcal{A}(S), D) > \frac{1}{8}\right) \le \frac{1}{9}$$

which contradicts with (2). We can show  $(1) \Rightarrow (2)$  by the fact that for any random variable  $X \in [0, 1]$  with  $\mathbb{E}[X] \geq \frac{1}{4}$ , then  $\mathbb{P}(X > \frac{1}{8}) \geq \frac{1}{8}$ . The proof is shown as follows

$$\begin{split} \mathbb{E}[X] &= \mathbb{E}[X\mathbf{1}(X \le \frac{1}{8})] + \mathbb{E}[X\mathbf{1}(X \in (\frac{1}{8}, 1])] \le \frac{1}{8} + \mathbb{E}[\mathbf{1}(X > \frac{1}{8})] \\ \Rightarrow \quad \mathbb{P}[X > \frac{1}{8}] = \mathbb{E}[\mathbf{1}(X > \frac{1}{8})] \ge \mathbb{E}[X] - \frac{1}{8} \ge \frac{1}{4} - \frac{1}{8} = \frac{1}{8} \end{split}$$

**Remark 2.**  $VC(\mathcal{H}) = \infty \Rightarrow \mathcal{H}$  is not PAC learnable, because  $VC(\mathcal{H}) = \infty$  implies that  $\forall m, \forall \mathcal{A}, \exists D$  realizable by  $\mathcal{H}$ 

$$\mathbb{P}_{S \sim D^m}\left(\operatorname{err}(\mathcal{A}(S), D) > \frac{1}{8}\right) > \frac{1}{9}$$

Proof of Theorem 3. We can rewrite the problem as minimax lower bound

$$\min_{\mathcal{A}} \max_{D:\text{realizable by } \mathcal{H}} \mathbb{E}_{S \sim D^m} \operatorname{err}(\mathcal{A}(S), D) \ge \frac{1}{4}$$
(3)

Define a family as distributions  $\mathcal{P} = \{D_b : b \in \{\pm 1\}^d\}$ . We want to show

$$\min_{\mathcal{A}} \mathbb{E}_{b \sim U(\pm 1)^d} \mathbb{E}_{S \sim D^m} \operatorname{err}(\mathcal{A}(S), D) \ge \frac{1}{4}$$

which implies (3). Find a set of unlabeled examples  $z_1, \dots, z_d$  shattered by  $\mathcal{H}$  and define  $D_b : \mathbb{P}(x = z_i, y = b_i) = \frac{1}{d} \ (\forall i = 1, \dots, d)$ . Our first observation is all  $D_b$ 's are realizable by  $\mathcal{H}$ . Denote  $\hat{h} = \mathcal{A}(S)$ . We are going to show

$$\forall \mathcal{A}, \quad \mathbb{E}_{b,S} \operatorname{err}(\hat{h}, D_b) \ge \frac{1}{4}$$

Given h, then  $\operatorname{err}(h, D_b) = \sum_{i=1}^d \frac{1}{d} \mathbf{1}(h(z_i) \neq b_i)$ . We want to show  $\sum_{i=1}^d \mathbb{E}_{b,S} \mathbf{1}(h(z_i) \neq b_i) \geq \frac{d}{4}$  by showing

$$\mathbb{P}_{b,S}(h(z_1) \neq b_1) \ge \frac{1}{4} \tag{4}$$

and we also can show this for other *i*'s. Denote unlabled sample set  $S_x = \{x_1, \dots, x_m\}$  are drawn i.i.d. from uniform $(\{z_1, \dots, z_d\})$ , then  $S = \{(x_1, y_1), \dots, (x_m, y_m)\}$  are determined by  $S_x$  and *b*. Then

$$\mathbb{P}_{b,S}(h(z_1) \neq b_1) \ge \mathbb{P}_{b,S_x}(h(z_1) \neq b_1, z_1 \notin S_x) = \mathbb{P}_{b,S_x}(h(z_1) \neq b_1 | z_1 \notin S_x) \cdot \mathbb{P}_{S_x}(z_1 \notin S_x)$$
(5)

Note that

$$\mathbb{P}(z_1 \in S_x) = \mathbb{P}(z_1 \in \bigcup_i \{x_i\}) \le \sum_{i=1}^m \mathbb{P}(z_1 = x_i) = \frac{m}{d} \le \frac{1}{2}$$

which implies  $\mathbb{P}_{S_x}(z_1 \notin S_x) \geq \frac{1}{2}$ . On the other hand, conditioned on  $z_1 \notin S_x$ ,  $\hat{h}(z_1)$  is independent of  $b_1$ , then

$$\mathbb{P}_{b,S_x}(\hat{h}(z_1) \neq b_1 | z_1 \notin S_x) = \frac{1}{2}$$

Thus, (5) can be rewritten as  $\mathbb{P}_{b,S}(\hat{h}(z_1) \neq b_1) \geq \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4}$ , which finishes the proof of (4) and the whole proof.

## 2 Review of what we learned

**Definition 4.**  $\mathcal{H}$  is said to satisfy the uniform convergence property if there exists a function  $f_u : (0,1)^2 \to \mathbb{N}$ such that for any D, for any  $\epsilon, \delta > 0$ , if  $m \ge f_u(\epsilon, \delta)$ , then w.p.  $1 - \delta$  over the draw of m i.i.d. training examples from D

$$\forall h \in \mathcal{H}, \quad |\operatorname{err}(h, S) - \operatorname{err}(h, D)| \le \epsilon$$

Theorem 5 (The fundamental theorem of statistical learning). The following statements are equivalent

1. H satisfies the uniform convergence property (Definition 4)

- 2. H is agnostic PAC learnable with ERM
- 3.  $\mathcal{H}$  is agnostic PAC learnable
- 4. H is (realizable) PAC learnable
- 5. H has finite VC dimension

Proof. By showing cycling implication.

- $1 \Rightarrow 2$ : set the sample size to be greater than  $f_u(\epsilon/2, \delta)$ , then by definition  $|\operatorname{err}(h, S) \operatorname{err}(h, D)| \le \epsilon/2$ w.p.  $1 - \delta$ , which is the sufficient condition for the ERM to achieve excess error rate at most  $\epsilon$  (as we discussed before)
- $2 \Rightarrow 3$ : trivial
- $3 \Rightarrow 4$ : seen before
- $4 \Rightarrow 5$ : just proved (Theorem 3)
- 5  $\Rightarrow$  1: last class of uniform convergence (by symmetrization, Rademacher random variables and Massart's Lemma)

Interpretation of finite VC dimension. For S which is a set of observations in the real-world, regard  $\mathcal{H}$  as scientific theory. If the scientific theory is too complicated (i.e.,  $\mathcal{H}$  has infinite VC dimension), then there might not be a reliable way of using this theory to make future prediction with scientific outcomes.

## 3 Appendix: Exercises

Problem 1. Can we bound the following term using Massart's Lemma?

$$\mathbb{E}_{S,S'\sim D^m}\left[\sup_{f\in\mathcal{F}}\mathbb{E}_S f(Z) - \mathbb{E}_{S'}f(Z)\right]$$
(6)

Problem 2. Upper bound (6) by

$$\mathbb{E}_{S \sim D^m} \sup_{f \in \mathcal{F}} \mathbb{E}_S f(Z) + \mathbb{E}_{S' \sim D^m} \sup_{f \in \mathcal{F}} \left( -\mathbb{E}_{S'} f(Z) \right)$$

without introducing Rademacher random variables. Will the proof still go through?