CSC 580 Principles of Machine Learning

01 Supervised learning; Decision Trees

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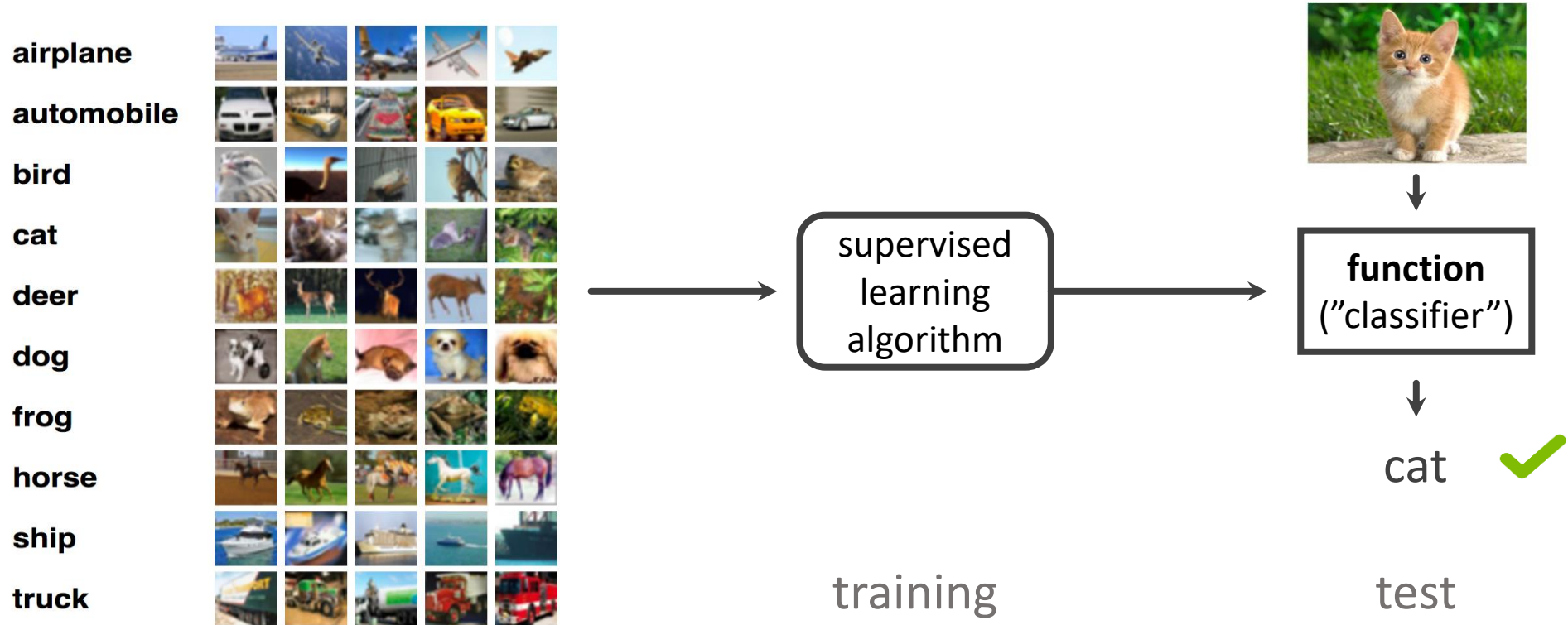
THE UNIVERSITY OF ARIZONA

The supervised learning problem

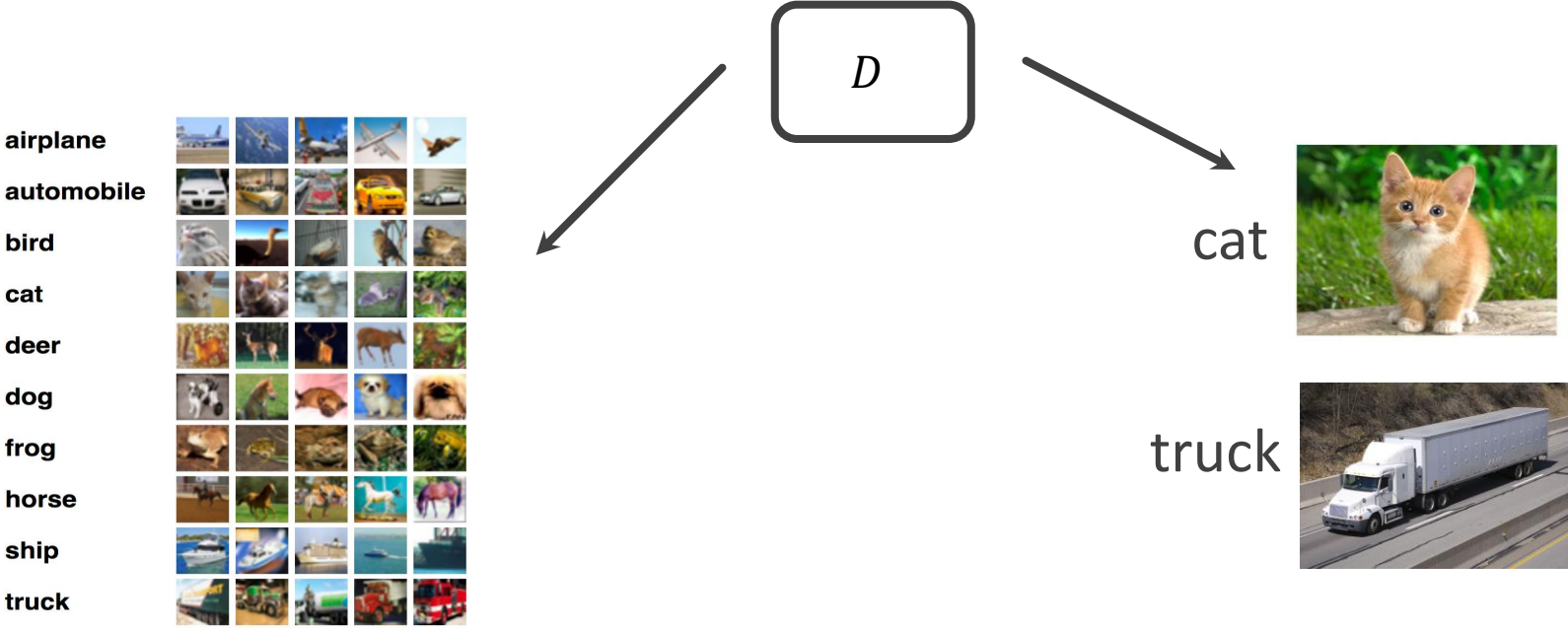# Recap: Supervised learning

- Training / test data: datasets comprised of *labeled examples*: pairs of (feature, label)

training   test

- Question: what makes a test procedure "reasonable"?
  - Test data: should it come from some other population? Should it overlap with the training data?
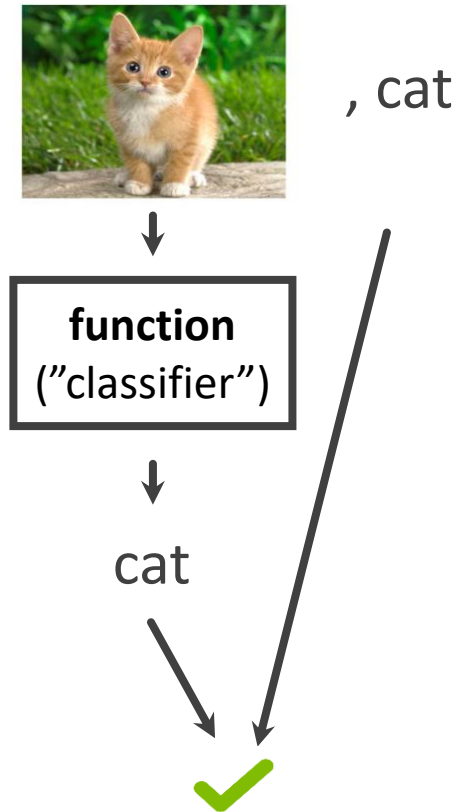 - Compare predicted labels with true labels: how?

Supervised learning: formal setup

- Training and test data are drawn independently from the same *data generating distribution D*
  - IID: independent and identically distributed
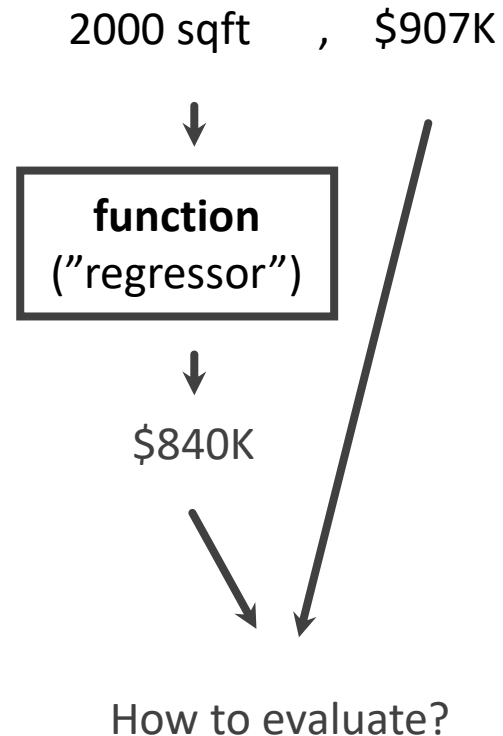- Training and test data are independent

D

cat

truck

Supervised learning: formal setup (cont'd)

- Scenario 1: classification

, cat

function
("classifier")

↓

cat ✓

- Scenario 2: regression

2000 sqft , $907K

↓

function
("regressor")

↓

$840K

How to evaluate?

- Loss function ℓ: measuring the prediction quality with respect to ground truth label

- Examples:
  - Zero-one loss
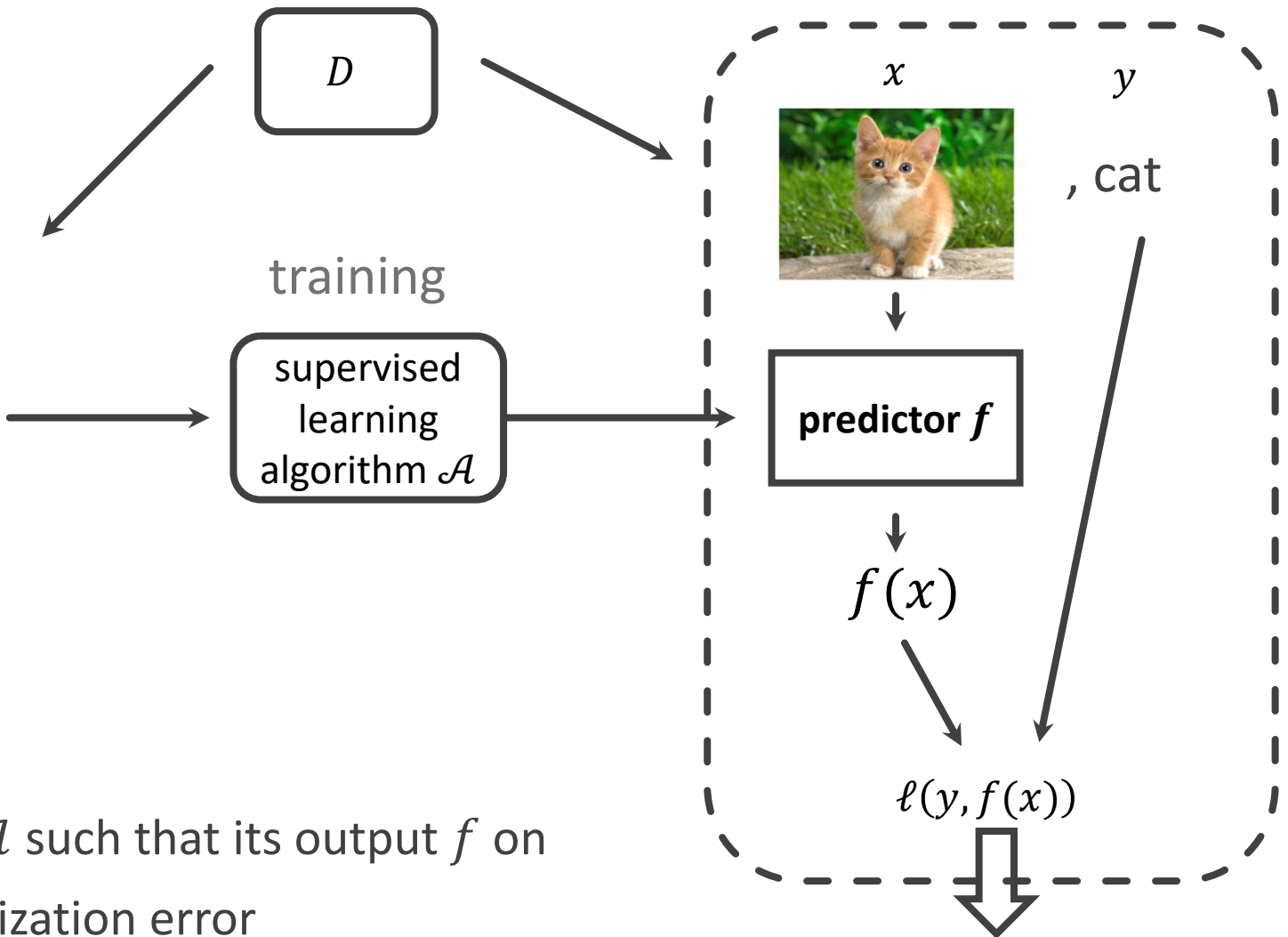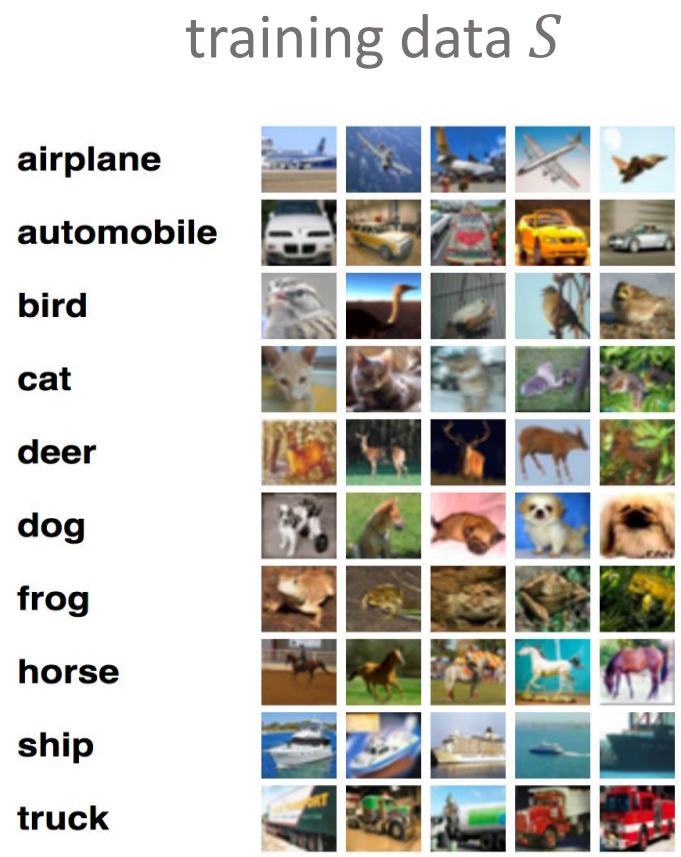 $\ell(y, \hat{y}) = I(y \neq \hat{y})$ - classification
  - Square loss
    $\ell(y, \hat{y}) = (y - \hat{y})^2$ - regression
  - Absolute loss:
    $\ell(y, \hat{y}) = |y - \hat{y}|$ - regression

Supervised learning setup: putting it together

training data S

D

x y

, cat

training

supervised
learning
algorithm $\mathcal{A}$

predictor f

$f(x)$

$\ell(y, f(x))$

- Goal: design learning algorithm $\mathcal{A}$ such that its output f on iid training data S has low generalization error

Generalization error: $L_D(f) = \mathrm{E}_{(x,y) \sim D} \; \ell(y, f(x))$

Supervised learning algorithm: decision trees

Example: course recommendation

- Build a software: given a student, recommend a set of courses that s/he likes

- Induced supervised learning problem:

course description
student info. $\longrightarrow$ predictor f $\longrightarrow$ rating $\in \{+, -\}$
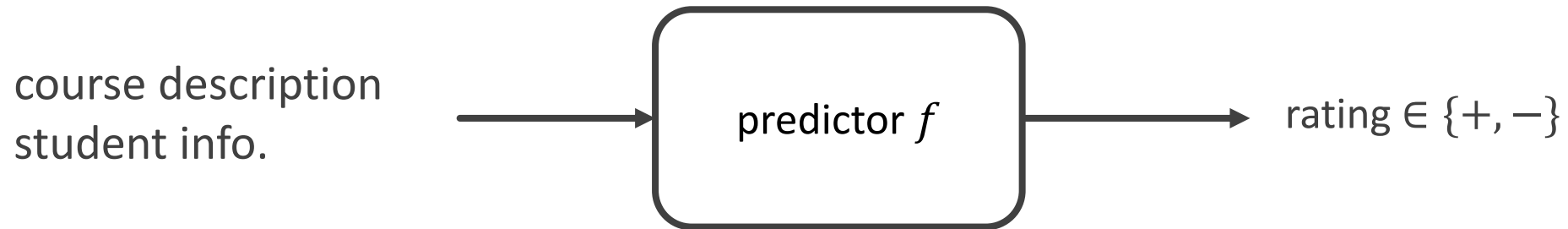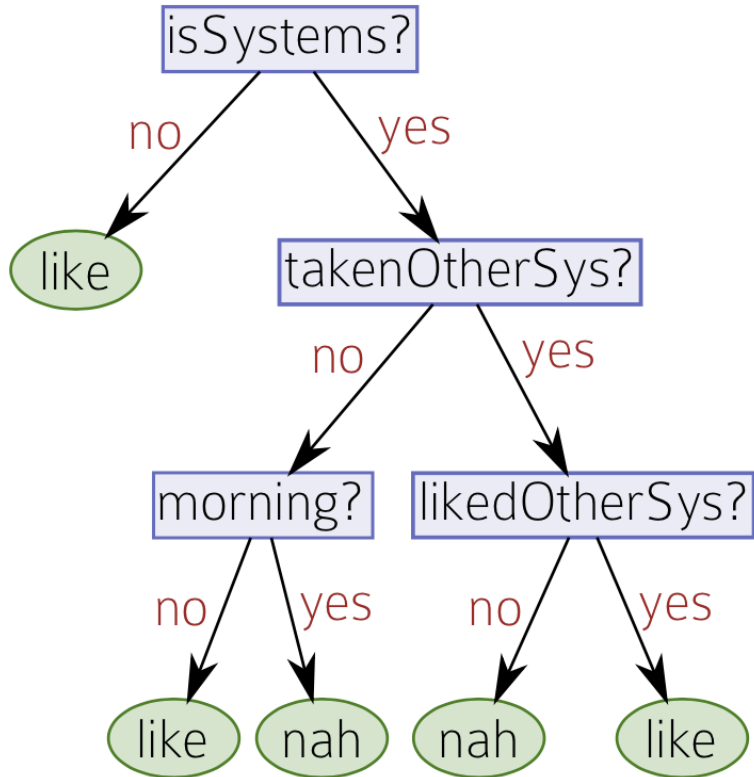
Decision trees: basic terminology

Figure 1.2: A decision tree for a course recommender system, from which the in-text "dialog" is drawn.

node
root node
leaf node
internal node

parent
children
subtree
depth

- Key advantage of using decision trees for decision making: *intepretability*

- Useful in consequential settings, e.g. medical treatment, loan approval, etc.

nodes organized in a tree-based structure, leading to a prediction (Fig. 1). The interpretability of decision trees allows physicians to understand why a prediction or stratification is being made, providing an account of the reasons behind the decision to subsequently accept or override the model's output. This interaction between humans and algorithms can provide

Prediction using decision trees

- Test: predict using a decision tree:

Algorithm 2 DECISIONTREETEST(*tree, test point*)

1: **if** *tree* is of the form LEAF(*guess*) **then**
2:     **return** *guess*
3: **else if** *tree* is of the form NODE(*f*, *left*, *right*) **then**
4:     **if** $f = no$ in *test point* **then**
5:         **return** DECISIONTREETEST(*left, test point*)
6:     **else**
7:         **return** DECISIONTREETEST(*right, test point*)
8:     **end if**
9: **end if**

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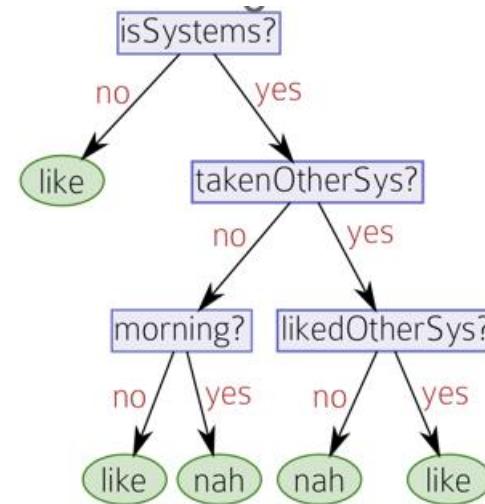
guess=prediction

left=no
right=yes

- Training: how to design a learning algorithm $\mathcal{A}$ that can build trees f from training data?

Course recommendation: simplified setup

training data S

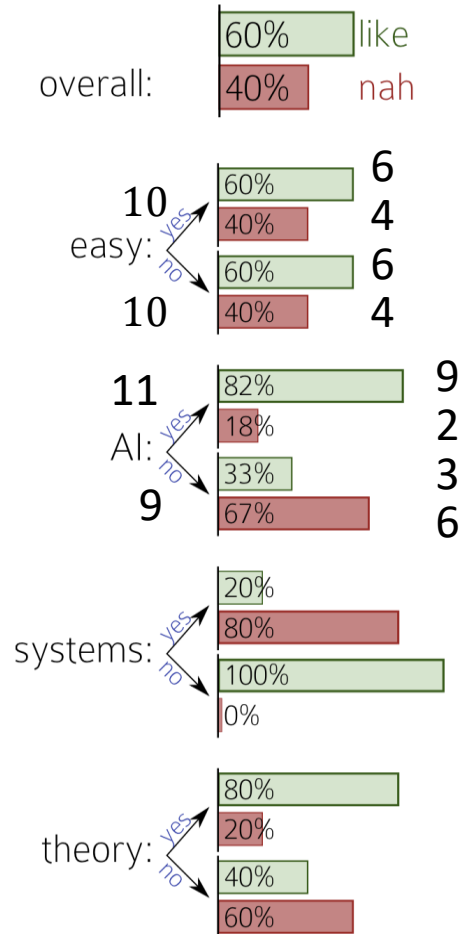| Rating	Easy?	AI?	Sys?	Thy?	Morning?
+2	y	y	n	y	n
+2	y	y	n	y	n
+2	n	y	n	n	n
+2	n	n	n	y	n
+2	n	y	y	n	y
+1	y	y	n	n	n
+1	y	y	n	y	n
+1	n	y	n	y	n
0	n	n	n	n	y
0	y	n	n	y	y
0	n	y	n	y	n
0	y	y	y	y	y
-1	y	y	y	n	y
-1	n	n	y	y	n
-1	n	n	y	n	y
-1	y	n	y	n	y
-2	n	n	y	y	n
-2	n	y	y	n	y
-2	y	n	y	n	n
-2	y	n	y	n	y

data point
feature
label

Generalization error vs. training error

- The training data $S = \{(x_i, y_i)\}_{i=1}^{m}$

- Given a predictor f, its training error $L_S(f) = \mathrm{E}_{(x,y) \sim S} \ell(y, f(x)) = \frac{1}{m} \sum_{i=1}^{m} \ell(y_i, f(x_i))$

- Consider zero-one loss, $\ell(y, \hat{y}) = I(y \neq \hat{y}) \Rightarrow L_S(f) = \mathrm{E}_{(x,y) \sim S} I(y \neq f(x)) = P_{(x,y) \sim S}(y \neq f(x))$

- Heuristic: f with low $L_S(f) \Rightarrow f$ with low $L_D(f)$
  - Also known as the "Empirical risk minimization" (ERM) approach
  - Issues with ERM?

- How easy is it to compute a decision tree f that minimize $L_S(f)$?
  - k-node decision tree, d-dimensional data $\Rightarrow$ at least $O(d^k)$ time complexity
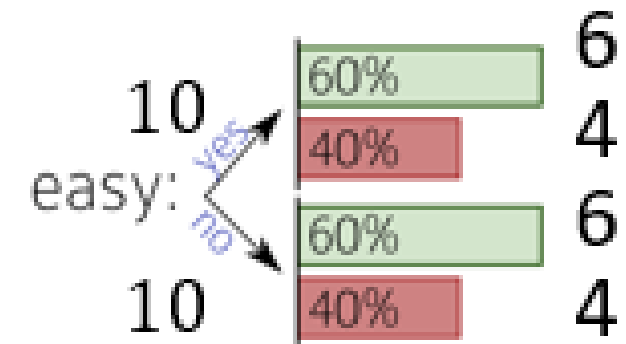 - Can we design efficient algorithms?

Decision tree training: single level case

- Q: if I could only ask one question (design a depth-1 tree), what question would I ask?

- Intuition: look at the histograms of labels for each feature

- Which feature is better, 'easy' or 'AI'?

- Best training accuracy using 'easy':

  (max(6,4) + max(6,4)) / 20 = 0.6

- Best training accuracy using 'AI':

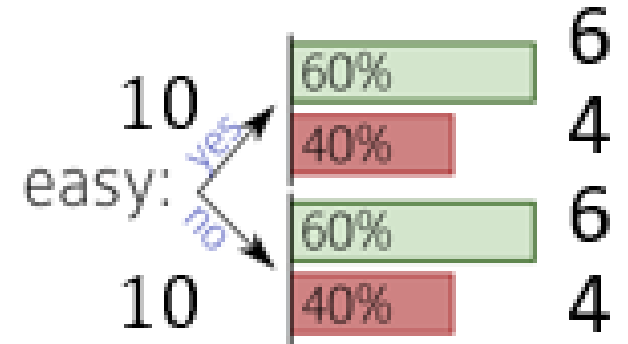 (max(9,2) + max(3,6)) / 20 = 0.75

Histogram calculation

Rating	Easy?	AI?	Sys?	Thy?	Morning?
+2	y	y	n	y	n
+2	y	y	n	y	n
+2	n	y	n	n	n
+2	n	n	n	y	n
+2	n	y	y	n	y
+1	y	y	n	n	n
+1	y	y	n	y	n
+1	n	y	n	y	n
0	n	n	n	n	y
0	y	n	n	y	y
0	n	y	n	y	n
0	y	y	y	y	y
-1	y	y	y	n	y
-1	n	n	y	y	n
-1	n	n	y	n	y
-1	y	n	y	n	y
-2	n	n	y	y	n
-2	n	y	y	n	y
-2	y	n	y	n	n
-2	y	n	y	n	y

easy: 10 yes → 60% = 6, 40% = 4
10 no → 60% = 6, 40% = 4

Decision tree training: single level case

- In formula:

- $\text{Score}(f, S) := \max \Big(P_S(y = +, x_f = yes), P_S(y = -, x_f = yes) \Big)$

$$+ \max \Big(P_S(y = +, x_f = no), P_S(y = -, x_f = no) \Big)$$
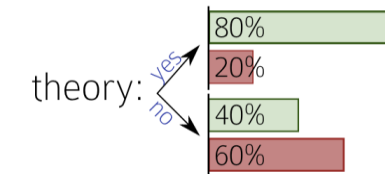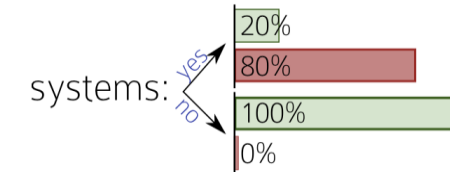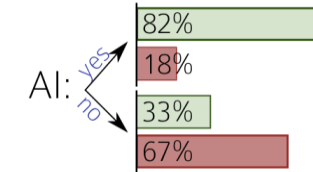
- Written in conditional probability:

Purity measure
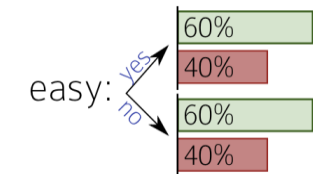
$$= \max \Big(P_S(y = + \mid x_f = yes), P_S(y = - \mid x_f = yes) \Big) \cdot P_S(x_f = yes)$$

$$+ \max \Big(P_S(y = + \mid x_f = no), P_S(y = - \mid x_f = no) \Big) \cdot P_S(x_f = no)$$

- e.g. $\text{Score}('easy', S) = \max(0.6, 0.4) \times 0.5 + \max(0.6, 0.4) \times 0.5 = 0.6$

Decision tree training: general level case

- High-level idea: greedy + divide & conquer

- Build the root of the tree greedily

- Build the left and left subtrees *recursively*

- When to stop the recursion?

overall:
60% like
40% nah

easy:
yes: 60% / 40%
no: 60% / 40%

AI:
yes: 82% / 18%
no: 33% / 67%

systems:
yes: 20% / 80%
no: 100% / 0%

theory:
yes: 80% / 20%
no: 40% / 60%

isSystems?
no → like
yes → takenOtherSys?
  no → morning?
    no → like
    yes → nah
  yes → likedOtherSys?
   no → nah
    yes → like
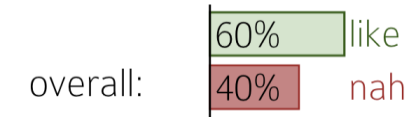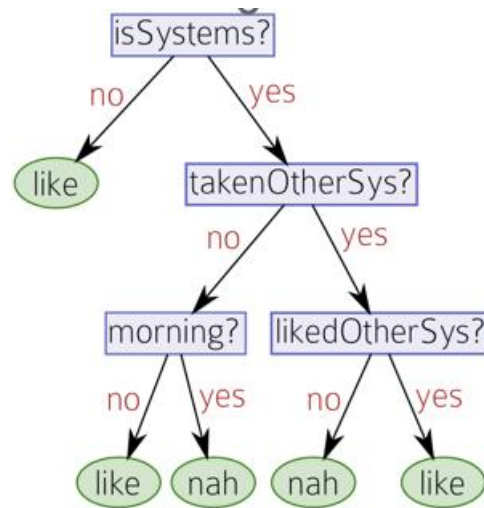
Algorithm 1 DECISIONTREETRAIN(*data, remaining features*)

1: *guess* ← most frequent answer in *data*   // default answer for this data
2: **if** the labels in *data* are unambiguous **then**
3:     **return** LEAF(*guess*)   // base case: no need to split further
4: **else if** *remaining features* is empty **then**
5:     **return** LEAF(*guess*)   // base case: cannot split further
6: **else**   // we need to query more features
7:     **for all** $f \in$ *remaining features* **do**
8:         $NO \leftarrow$ the subset of *data* on which f=*no*
9:         $YES \leftarrow$ the subset of *data* on which f=*yes*
10:        *score*[*f*] ← # of majority vote answers in NO
11:                      + # of majority vote answers in YES
                                   // the accuracy we would get if we only queried on *f*
12:    **end for**
13:    $f \leftarrow$ the feature with maximal *score(f)*
14:    $NO \leftarrow$ the subset of *data* on which f=*no*
15:    $YES \leftarrow$ the subset of *data* on which f=*yes*
16:    *left* ← DECISIONTREETRAIN(NO, *remaining features* \ {f})
17:    *right* ← DECISIONTREETRAIN(YES, *remaining features* \ {f})
18:    **return** NODE(*f, left, right*)
19: **end if**

answer=label
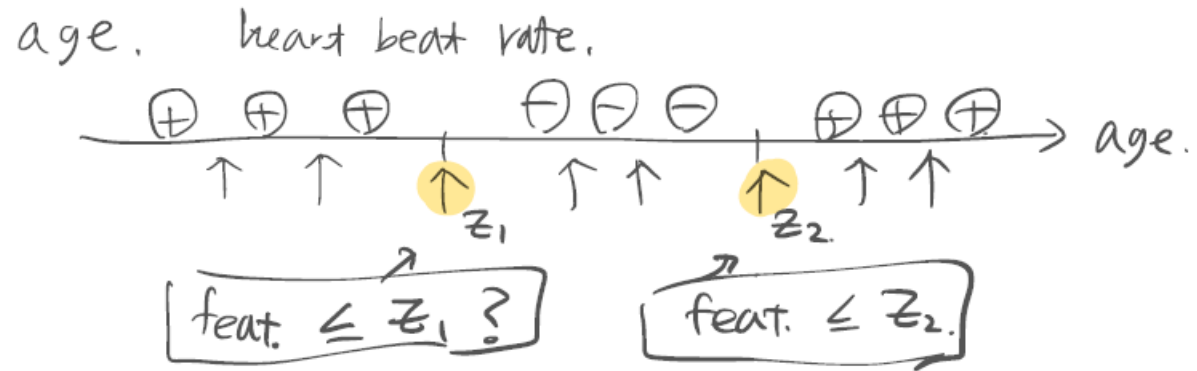unambiguous=achieves 100% acc.
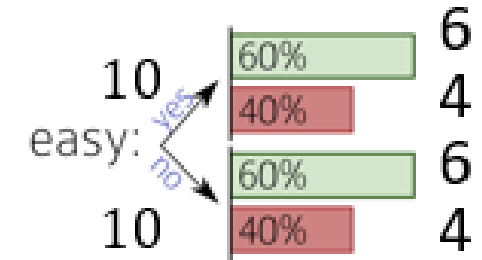
$$\text{Score}(f, S) := \max\left(P_S(y = +, x_f = yes), P_S(y = -, x_f = yes)\right)$$
$$+\max\left(P_S(y = +, x_f = no), P_S(y = -, x_f = no)\right)$$

Q: is this algorithm guaranteed to terminate?

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Dealing with various types of features

- Binary: $x_f \in \{0,1\}$
  - Node: $x_f = 0$?

- Categorical: $x_f \in \{1,2,\dots,C\}$
  - Node: $x_f \in \{i_1,\dots,i_l\}$?

- real value: $x_f \in \mathbb{R}$
  - Node: $x_f \leq z$?

Example: spam filtering I

- ▶ Spam dataset
- ▶ 4601 email messages, about 39% are spam
- ▶ Classify message by spam and not-spam
- ▶ 57 features
  - ▶ 48 are of the form "percentage of email words that is (WORD)"
  - ▶ 6 are of the form "percentage of email characters is (CHAR)"
  - ▶ 3 other features (e.g., "longest sequence of all-caps")
- ▶ Final tree after pruning has 17 leaves, 9.3% test error rate
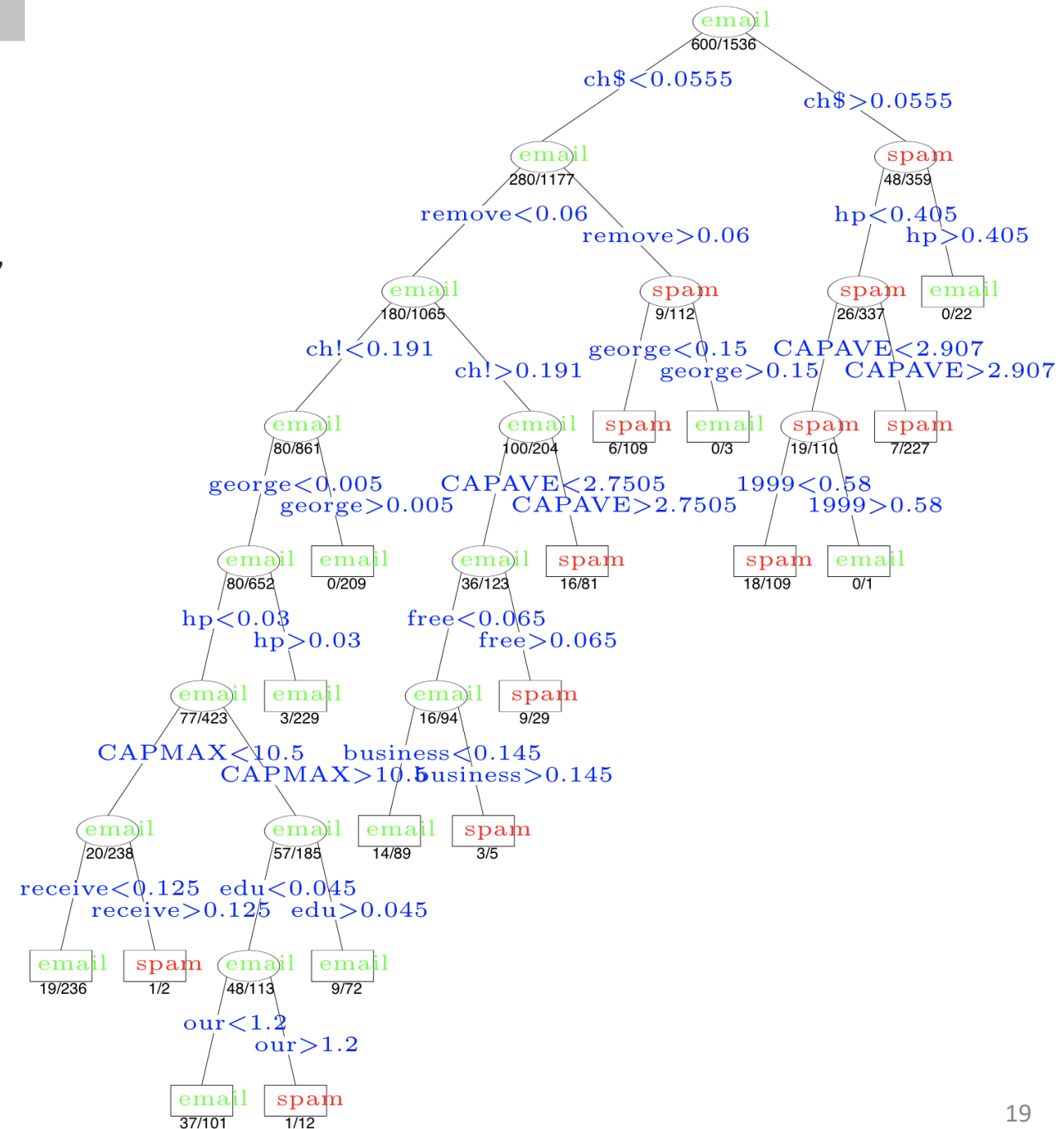
Q: what is the best depth-0 decision tree, and what is its accuracy?

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Decision tree training: generalized scores

- Score(f) = a measure of **informativeness** of f
- Approach: find a split that maximizes informativeness / reduces uncertainty ("chaoticness")
- Uncertainty measures of population:

Notions of uncertainty: binary case ($\mathcal{Y} = \{0, 1\}$)

Suppose in a set of examples $S \subseteq \mathcal{X} \times \{0, 1\}$, a p fraction are labeled as 1
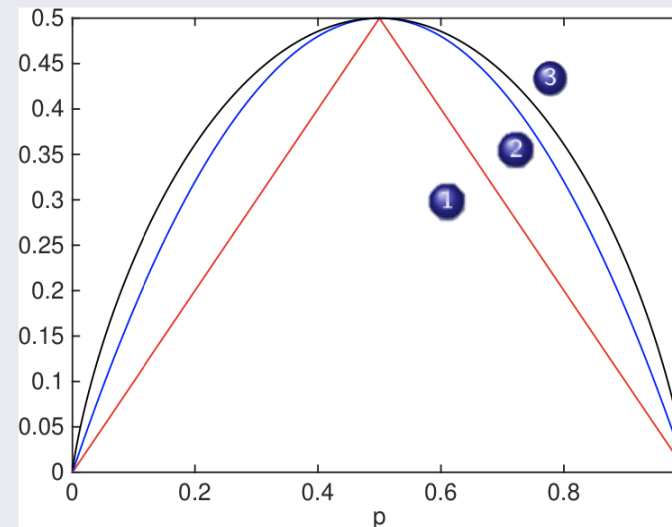
❶ Classification error:
$$u(S) := \min\{p, 1 - p\}$$

❷ Gini index:
$$u(S) := 2p(1 - p)$$

❸ Entropy:
$$u(S) := p \log \frac{1}{p} + (1-p) \log \frac{1}{1 - p}$$

(3) is divided by 2 so the plot looks comparable

log here is base-2

Decision tree training: generalized scores

- Multiclass classification setting: $\mathcal{Y} = \{1, \dots, K\}$

Notions of uncertainty: general case

Suppose in $S \subseteq \mathcal{X} \times \mathcal{Y}$, a $\boxed{p_k}$ fraction are labeled as k (for each $k \in \mathcal{Y}$).

① **Classification error:**

$$u(S) := 1 - \max_{k \in \mathcal{Y}} p_k$$

② **Gini index:**

$$u(S) := 1 - \sum_{k \in \mathcal{Y}} p_k^2$$
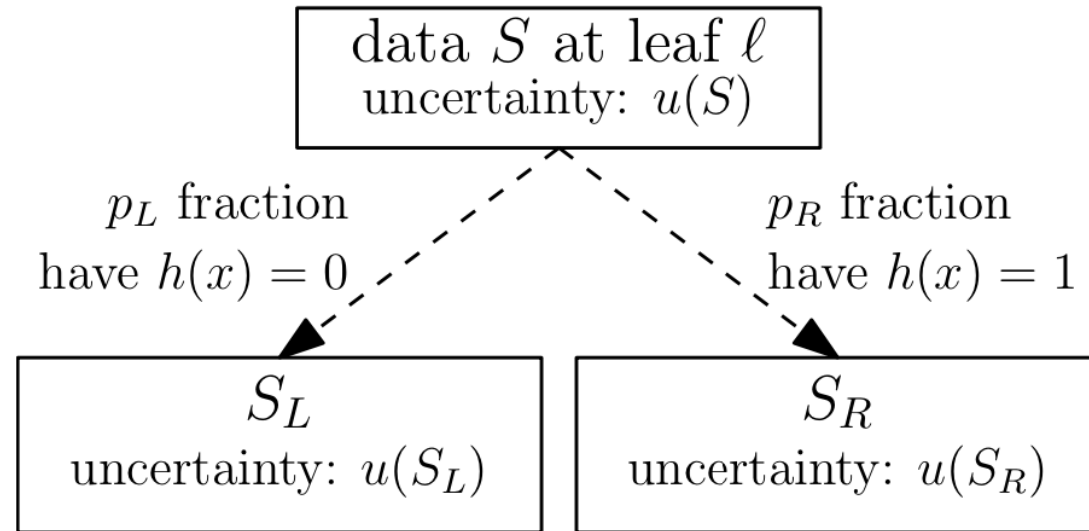
③ **Entropy:**

$$u(S) := \sum_{k \in \mathcal{Y}} p_k \log \frac{1}{p_k}$$

Each is *maximized* when $p_k = 1/|\mathcal{Y}|$ for all $k \in \mathcal{Y}$
(i.e., equal numbers of each label in S)

Each is *minimized* when $p_k = 1$ for a single label $k \in \mathcal{Y}$
(so S is **pure** in label)

Decision tree training: generalized scores

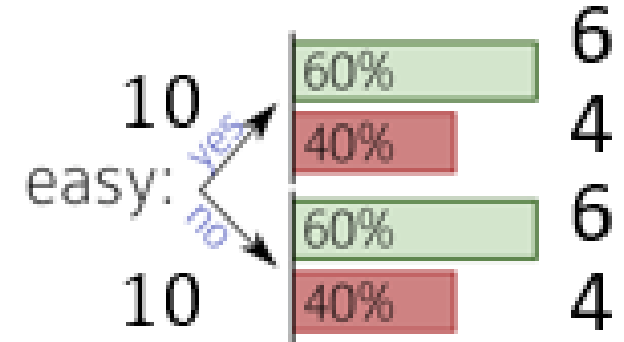Suppose the data S at a leaf ℓ is split by a rule h into S_L and S_R, where $p_L := |S_L|/|S|$ and $p_R := |S_R|/|S|$

The **reduction in uncertainty** from using rule h at leaf ℓ is

$$u(S) - \left(p_L \cdot u(S_L) + p_R \cdot u(S_R) \right) \quad \boxed{=: \text{Score}(h, S) \ \ (\text{Generalized})}$$

Generalized splitting criteria in action

- Entropy uncertainty:

$$u(S) = \sum_{y_0 \in \{+,-\}} P_S(y = y_0) \log \frac{1}{P_S(y=y_0)}$$

- $\text{Score}(S, f) = u(S) - \left(p_L \, u(S_L) + p_R \, u(S_R) \right)$

$$\boxed{P_S(x_f = no)}$$

$$\boxed{\sum_{y_0 \in \{+,-\}} P_S(y = y_0 \mid x_f = no) \log \frac{1}{P_S(y = y_0 \mid x_f = no)}}$$

- E.g. for the above S, $\text{Score}('easy', S) = 0$, because:
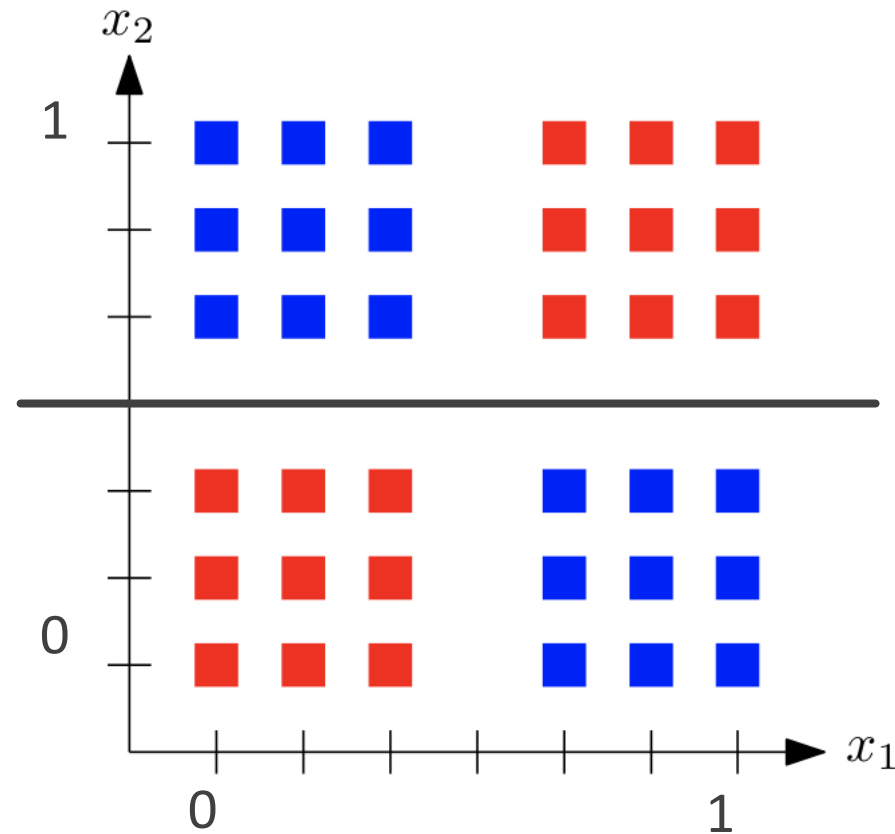 - $u(S) = 0.6 \log \frac{1}{0.6} + 0.4 \log \frac{1}{0.4}, \; p_L = 0.5, p_R = 0.5$
  - $u(S_L) = u(S_R) = 0.6 \log \frac{1}{0.6} + 0.4 \log \frac{1}{0.4}$

- In this case, $\text{Score}(S, f)$ is also known as the **mutual information** between x_f and y under P_S

Stop splitting when there is no reduction in uncertainty? This is a bad idea!

The 'XOR' data: Suppose $\mathcal{X} = \mathbb{R}^2$ and $\mathcal{Y} = \{\text{red}, \text{blue}\}$, and the data is as follows:
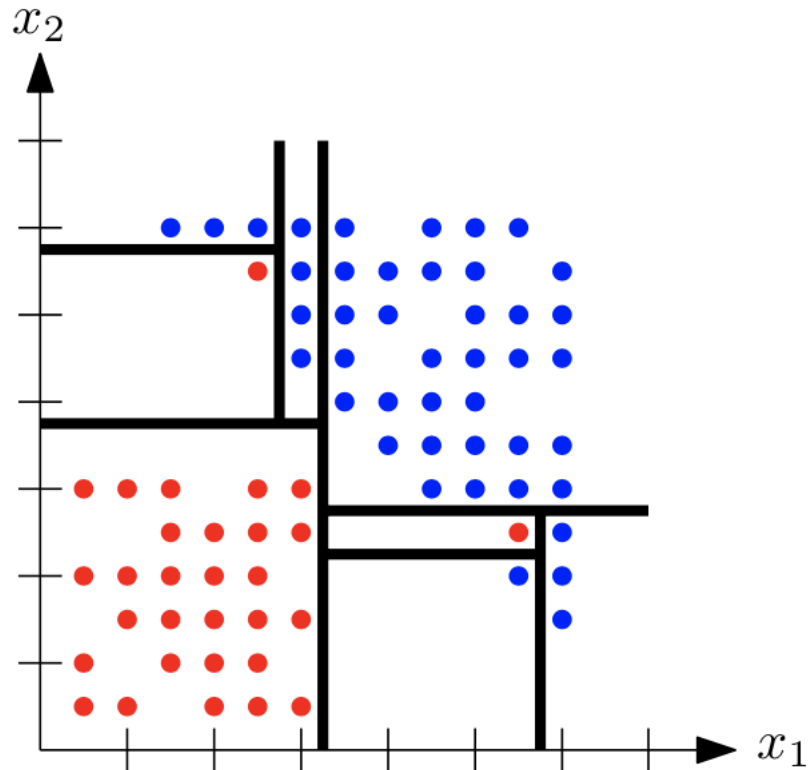
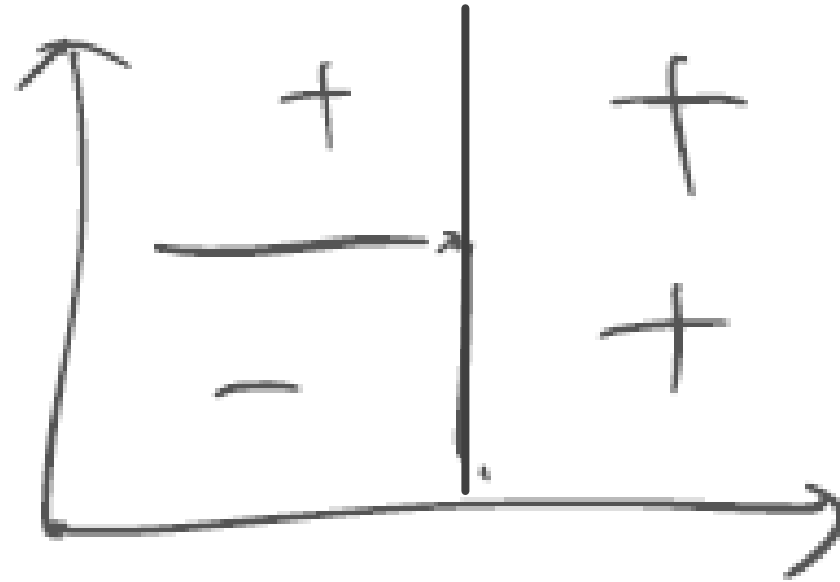| A	B	A XOR B
0	0	0
0	1	1
1	0	1
1	1	0

- Any axis-aligned split has no reduction on uncertainty on S
- However, a depth-2 decision tree (with axis-aligned splits) has zero training error

<u>Overfitting</u> can happen

- "Spurious" patterns can be learned.

A better alternative:

Next lecture (8/29)

- Supervised learning: what to do if the data distribution is *known*?

- Models, parameters, hyperparameters

- Practical considerations

- Assigned reading: CIML Chap. 2 (Limits of learning)

- HW 0 due